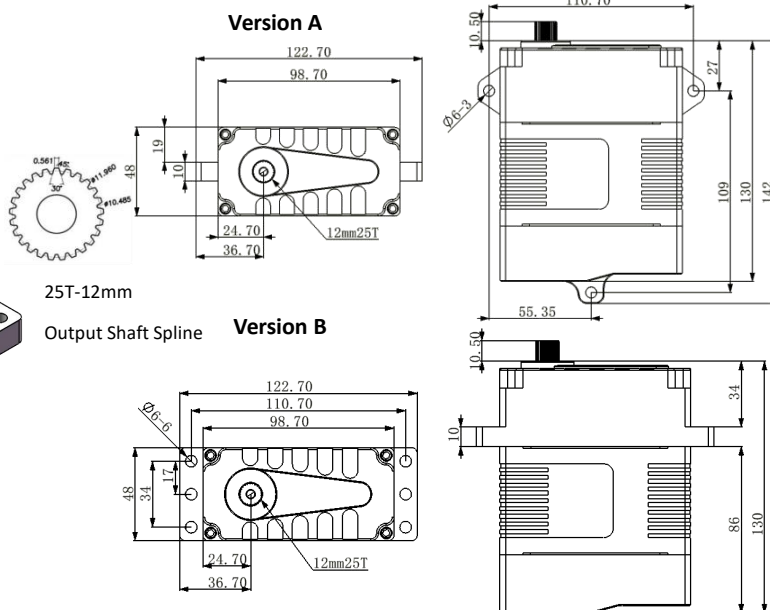
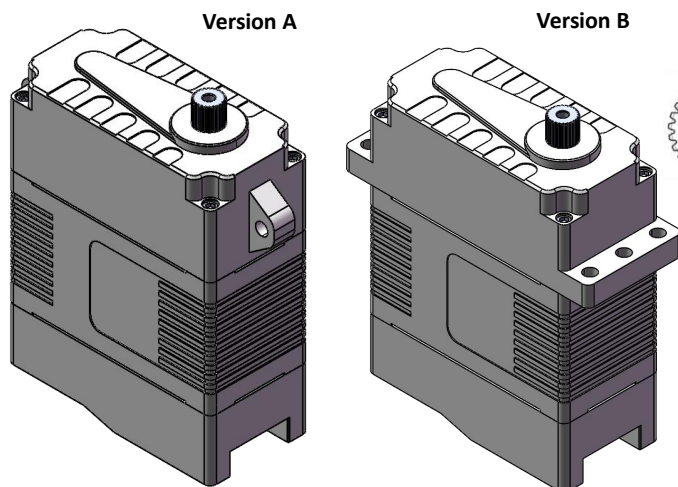


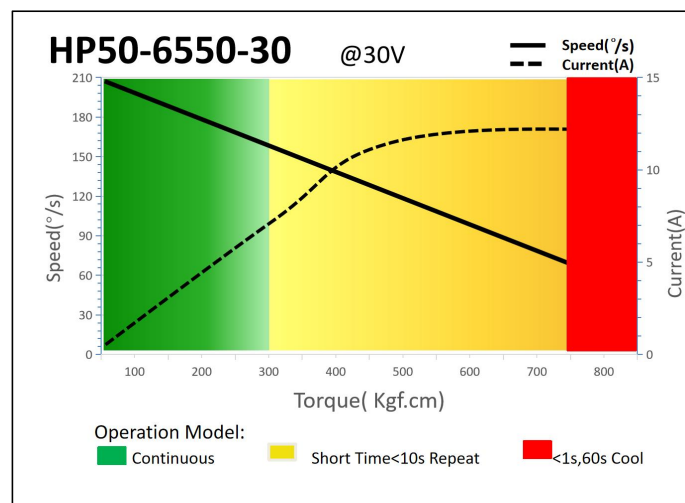
Technical Specification



1. Operating Data

Rated Voltage	DC30V
Voltage Range	DC20V-32V
No-load current	55mA
Stalling Torque	750Kgf.cm
No load speed	210°/sec
Rated Speed	150°/sec
Stalling Current	12.0A
Rated Torque	300Kgf.cm
Rated Current	6.4A
Working Frequency	1520us/333Hz
Pulse Width	500us-2500us
Temperature Range	-30°C.....+75°C
Default Travel Angle	±100°=200° Total angle
Dead Band	2us
Gear Backlash	≤0.5°
Command Signal	PWM/CANOPEN 2.0B
Dimensions	98.7*48*130mm(±0.5mm)
Weight	1350g±10%
Case Material	Aluminum Alloy
Motor Type	Brushless DC Motor
Gear Set Material	Hardened Steel
Position Sensor:	Contactless
Ball Bearing:	6BB
Shielded Connecting Cable	J30J-15TJL

2. Performance



3. Command Signal

3.1 PWM Command Interface

Signal Voltage	HIGH: min.3.3V, max.5.0V Low: min.0.0V, max.1.5V
Pulse Width	500us-2500us
Pulse Width for Position	1000us/1500us/2000us -50°/ 0°/+50°

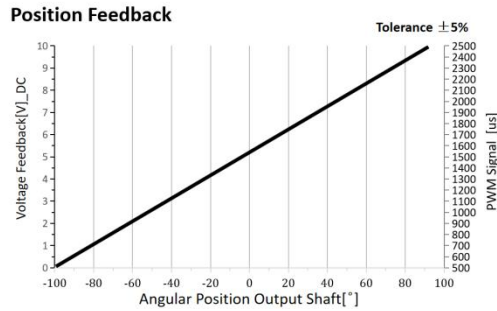
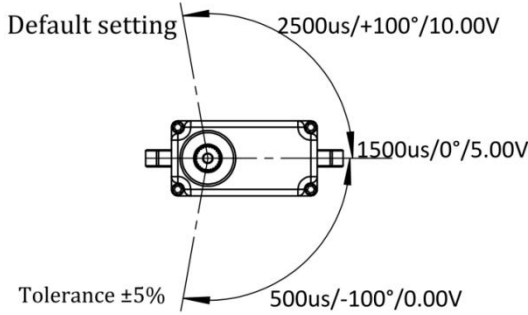
3.2 CAN Bus Command Interface

Baud-Rate	500Kbps
Node number	0 x25 (range 1 ~ 127, 0 is radio)
Communication	CAN Open

3.3 Position Feedback Signal

3.3.1 PWM Feedback

The Position Feedback signal (Pos FB) is an analog output signal with a voltage value which is directly related to the output shaft's angular position. Reference is **FB -**.



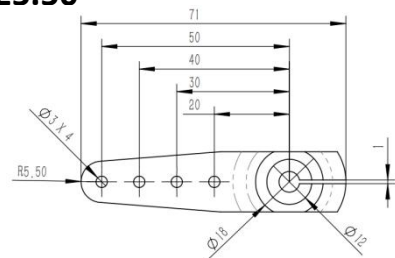
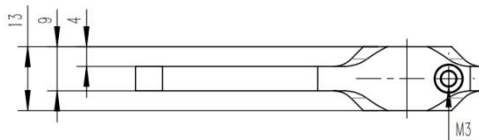
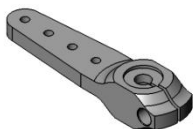
3.3.2 CANBUS Feedback

Integrated in the Bus protocol a Feedback Value, including the Angle position, Temperature, current value. Value read by sending request command. Provide the details of the bus in the document.

4. Electrical Connection - J30J-15ZKP

Pin	Description	Pin	Description
1	DC + Supply Voltage	10	PWM Command Signal
2		11	PWM Signal GND
3			
4		12	FB +
5	DC- Supply Ground	13	FB -
6		14	CAN_H
7			
8		15	CAN_L
9	NC Do not connect		

5. Accessories: Aluminum Servo Horn , Item No.: 1225.50



6. Item Number System

